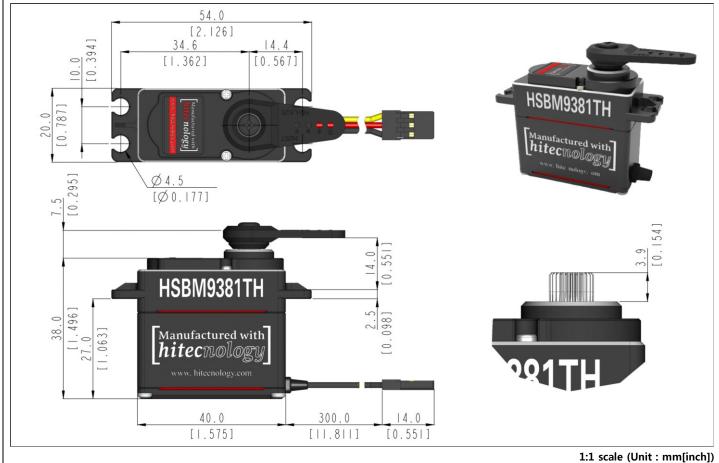
HSB-M9381TH General Specification.



Control System	PWM			-
Position Sensor Type	Contactless Magnetic Encoder			-
Motor Type	BLDC			At the Max voltage, it is recommended to be used only
Operating Voltage Range	4.0 ~ 8.4V			
Voltage	-	6.0V	7.4V	for a short time duration.
No Load Speed	-	0.17sec/60°	0.14sec/60°	At 25°C(±10%), 45%RH(±10%) measurement environment
Stall Torque	-	34.0kgf·cm (472.2 oz·in)	34.0kgf·cm (472.2 oz·in)	
Peak Efficiency Torque	-	6.8kgf·cm (94.4 oz·in)	6.8kgf·cm (94.4 oz·in)	
Standing Current	-	27mA	27mA	
No Load Running Current	-	250mA	250mA	
Stall Current	-	2,700mA	2,100mA	
Deadband	-	1μs	1µs	
Operating Travel	Default: ±60°, Programmable: Max 300° / Pulse Width: 900~2100µs(Center:1500µs)			-
Continuous Rotation	n/a			-
Operating Temperature Range	-20°C ~ +70°C (-4°F ~+158°F)			-
Storage Temperature Range	-30°C ~ +80°C (-22°F ~+176°F)			-
Connector Wire Length	300mm (11.811inch)			1. SIGNAL 2. VCC 3. GND
Connector Wire Gauge	20AWG			
Dimensions	40.0mm x 20.0mm x 38.0mm (1.575inch x 0.787inch x 1.496inch)			General Tolerance ±0.1mm
Weight	78.0g (2.751oz)			Excluding the weight of Horn
Bearing Type	2 Ball Bearing			-
Case Material	Aluminum Alloy			-
Gear Material	1 Metal-Plastic & 3 Titanium Alloy Gears			-
Gear Train Backlash	Max 0.5°			-
Horn Gear Spline	25T(Ø6)			-
IP-Rating	IP54			-
Servo Amplifier Type	16bit Programmable Digital			-



- This product should not be used directly on the human body for medical purposes.
- This product should not be used for war weapons.
- All specifications are subject to change without notice.
- Be careful as strong magnetic fields may cause malfunction of the product.



